## Features

■ USB 2.0 Hub
■ Four Downstream Ports
■ Multiple Transaction Translators - One per Downstream Port for Maximum Performance
■ VID, PID, and DID configured from External SPI EEPROM
■ 24 MHz External Crystal
■ Small Package - Quad Flat Pack, No Leads (QFN)

- Integrated Upstream Pull Up Resistor
- Integrated Downstream Pull Down Resistors for all Downstream Ports

■ Integrated Upstream and Downstream Series Termination Resistors

■ Configurable with External SPI EEPROM
a Number of Active Ports
a Number of Removable Ports
a Maximum Power
a Hub Controller Power
a Power On Timer
口 Overcurrent Timer
a Disable Overcurrent Timer
a Enable Full Speed Only
a Disable Port Indicators

- Gang Power Switching
a Enable Single TT Mode Only
a Enable NoEOP at EOF1

Logic Block Diagram


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## Introduction

Cypress's TetraHub™ is a high performance self powered Universal Serial Bus (USB) 2.0 hub. The Tetra architecture provides four downstream USB ports, with a Transaction Translator (TT) for each port, making it the highest performing hub possible. This single-chip device incorporates one upstream and four downstream USB transceivers, a serial Interface Engine (SIE), USB hub controller and repeater, and four TTs. It is suitable for standalone hubs, motherboard hubs, and monitor hub applications.
Being a fixed-function USB device, there is no risk or added engineering effort required for firmware development. The developer does not need to write any firmware for their design. The CY4602 Tetrahub USB 2.0 4-port Hub Reference Design Kit provides all materials and documents needed to move rapidly into production. The reference design kit includes board schematics, bill of materials, Gerber files, Orcad files, key application notes, and product description.
CY7C65640A-LFXC is a functional and pin equivalent die revision of Cypress's CY7C65640-LFXC. Changes were made to improve device performance.

## TetraHub Architecture

The Logic Block Diagram on page 1 shows the TetraHub Architecture.

## USB Serial Interface Engine (SIE)

The SIE enables the CY7C65640A to communicate with the USB host through the USB repeater component of the hub. The SIE handles the following USB bus activity independently of the Hub Control Block:

- Bit stuffing/unstuffing

■ Checksum generation/checking

- ACK/NAK/STALL
- TOKEN type identification
- Address checking.


## Hub Controller

The hub control block does the following protocol handling at a higher level:

- Coordinate enumeration by responding to SETUP packets
- Fill and empty the FIFOs
- Suspend/Resume coordination

■ Verify and select DATA toggle values

- Port power control and overcurrent detection.

The Hub controller provides status and control and permits host access to the hub.

## Hub Repeater

The hub repeater manages the connectivity between upstream and downstream facing ports that are operating at the same speed. It supports full/low speed connectivity and high speed connectivity. According to USB 2.0 specification, the hub repeater provides the following functions:

- Sets up and tears down connectivity on packet boundaries
- Ensures orderly entry into and out of the suspend state, including proper handling of remote wakeups.


## Transaction Translator

The TT translates data from one speed to another. A TT takes high speed split transactions and translates them to full/low speed transactions when the hub is operating at high speed (the upstream port is connected to a high speed host controller) and has full/low speed devices attached. The operating speed of a device attached on a downstream facing port determines whether the routing logic connects a port to the transaction translator or hub repeater section. If a low or full speed device is connected to the hub operating at high speed, the data transfer route includes the transaction translator. If a high speed device is connected to this high speed hub the route only includes the repeater and no transaction translator; the device and the hub are in conformation with respect to their data transfer speed. When the hub is operating at full speed (the upstream port is connected to a full speed host controller), a high speed peripheral does not operate at its full capability. These devices only work at 1.1 speed. Full and low speed devices connected to this hub operate at their 1.1 speed.

## Applications

- Standalone Hubs
- Motherboard Hubs
- Monitor Hub applications

■ External Personal Storage Drives

- Port Replicators
- Portable Drive
- Docking Stations


## Functional Overview

The Cypress TetraHub USB 2.0 hub is a high performance, low-system-cost solution for USB. This hub integrates 1.5 k upstream pull up resistors for full speed operation and all downstream 15 k pull down resistors and series termination resistors on all upstream and downstream D+ and D- pins. This results in optimization of system costs by providing built-in support for the USB 2.0 specification.

## System Initialization

On power up, the TetraHub reads an external SPI EEPROM for configuration information. At the most basic level, this EEPROM has the Vendor ID (VID), Product ID (PID), and Device ID (DID) for the customer's application. For more specialized applications, other configuration options can be specified. See Configuration Options on page 12 for more details.
After reading the EEPROM, if BUSPOWER (connected to the upstream VBus) is high, TetraHub enables the pull up resistor on the $\mathrm{D}+$ to indicate that it is connected to the upstream hub, after which a USB bus reset is expected. During this reset, TetraHub initiates a chirp to indicate that it is a high speed peripheral. In a USB 2.0 system, the upstream hub responds with a chirp sequence, and TetraHub is in a high speed mode, with the upstream D+ pull up resistor turned off. In USB 1.x systems, no such chirp sequence from the upstream hub is seen, and TetraHub operates as a normal 1.x hub (operating at full speed).

## Enumeration

After a USB Bus Reset, TetraHub is in an unaddressed, unconfigured state (configuration value set to 0 ). During the enumeration process, the host sets the hub's address and configuration by sending a SetCongfiguration request. Changing the hub address restores it to an unconfigured state.
For high speed multi-TT support, the host must also set the alternate interface setting to 1 (the default mode is single TT). After the hub is configured, the full hub functionality is available.

## Multiple Transaction Translator Support

After TetraHub is configured in a high speed system, it is in single TT mode. The host may then set the hub into multiple TT mode by sending a SetInterface command. In multiple TT mode, each full speed port is handled independently and thus has a full 12 Mbps bandwidth available. In Single TT mode, all traffic from the host destined for full or low speed ports are forwarded to all of those ports. This means that the 12 Mbps bandwidth is shared by all full and low speed ports.

## Downstream Ports

TetraHub supports a maximum of four downstream ports, each of which may be marked as usable or removable in the extended configuration (0xD2 EEPROM load, see section). Downstream D+ and D- pull down resistors are incorporated in TetraHub for each port. Prior to the hub being configured, the ports are driven SEO (Single Ended Zero, where both D+ and D- are driven low) and are set to the unpowered state.

After the hub is configured, the ports are not driven, and the host may power the ports by sending a SetPortPower command to each port. After a port is powered, any connect or disconnect event is detected by the hub. Any change in the port state is reported by the hub back to the host through the Status Change Endpoint (endpoint 1). Upon receipt of SetPortReset command from the host, the hub does the following:
■ Drive SEO on the corresponding port

- Put the port in an enabled state

■ Enable the green port indicator for that port (if not previously overridden by the host)

- Enable babble detection after the port is enabled.

Babble consists of either unterminated traffic from a downstream port (or loss of activity), or a non-idle condition on the port after EOF2. If babble is detected on an enabled port, that port is disabled. A ClearPortEnable command from the host also disables the specified port.
Downstream ports can be individually suspended by the host with the SetPortSuspend command. If the hub is not suspended, any resume will be confined to that individual port and reflected to the host through a port change indication in the Hub Status Change Endpoint. If the hub is suspended, a resume on this port will be forwarded to the host, but other resume events will not be seen on that port. The host may resume the port by sending a ClearPortSuspend command.

## Upstream Port

The upstream port includes the transmitter and the receiver state machine. The transmitter and receiver operate in high speed and full speed depending on the current hub configuration.
The transmitter state machine monitors the upstream facing port while the hub repeater has connectivity in the upstream direction. This monitoring activity prevents propagation of erroneous indications in the upstream direction. In particular, this machine prevents babble and disconnect events on the downstream facing ports of this hub from propagating and causing the hub to be disabled or disconnected by the hub to which it is attached. This enables the hub to only disconnect the offensive port on detecting a babble from it.

## Power Switching

TetraHub includes interface signals for external port power switches. Both ganged and individual (for each port) configurations are supported, with individual switching being the default. Initially all ports are unpowered. After enumerating, the host may power each port by sending a SetPortPower command for that port. The power switching and overcurrent detection of downstream ports is managed by control pins connected to an external power switch device. PWR [n]\# output pins of the CY7C65640A series are connected to the respective external power switch's port power enable signals. (Note that each port power output pin of the external power switch must be bypassed with an electrolytic or tantalum capacitor as required by the USB specification. These capacitors supply the inrush currents, which occur during downstream device hot-attach events.)

## Overcurrent Detection

Overcurrent detection includes timed detection of 8 ms by default. This parameter is configured from the external EEPROM in a range of 0 ms to 15 ms for both an enabled port and a disabled port individually. Detection of over on downstream ports is managed by control pins connected to an external power switch device.
The OVR[n]\# pins of the CY7C65640A series are connected to the respective external power switch's port overcurrent indication (output) signals. Upon detecting an overcurrent condition, the hub device reports the overcurrent condition to the host and disables the PWR\# output to the external power device.

## Port Indicators

The USB 2.0 port indicators are also supported directly by TetraHub. According to the specification, each downstream port of the hub supports an optional status indicator. The presence of indicators for downstream facing ports is specified by bit 7 of the wHubCharacteristics field of the hub class descriptor. The default TeraHub descriptor specifies that port indicators are supported (wHubCharacteristics, bit 7 is set). If port indicators are not included in the hub, EEPROM should disable this.
Each port indicator is strategically located directly on the opposite edge of the port which it is associated with. The indicator provides two colors: green and amber. This is implemented as two separate LEDs, one amber and the other green.

A combination of hardware and software control is used to inform the user of the current status of the port or the device attached to the port and to guide the user through problem resolution. Colors and blinking are used to provide information to the user. The significance of the color of the LED depends on the operational mode of the TetraHub. There are two modes of operation for the TetraHub port indicators: automatic and manual.
On power up, the TeraHub defaults to automatic mode, where the color of the port indicator (green, amber, off) indicates the functional status of the TetraHub port. In automatic mode, TetraHub turns on the green LED whenever the port is enabled and the amber LED when it detects an overcurrent condition. The color of the port indicator is set by the port state machine. Blinking of the LEDs is not supported in automatic mode. Table 1 identifies the mapping of color to port state in automatic mode.
In manual mode, the indicators are under the control of the host, which can turn on one of the LEDs, or leave them off. This is done by a system software USB Hub class request. Blinking of the LEDs is supported in manual mode. The port indicators enable the user to intervene on any error detection. For example, when babble is detected on plugging in a defective device, or on occurrence of an overcurrent condition, the port indicators corresponding to the downstream port blink green or only light the amber LED, respectively. Table 2 displays the color definition of the indicators when TetraHub is in manual mode.

Table 1. Automatic Port State to Port Indicator Color Mapping

| Port <br> Switching | Downstream Facing Hub Port State |  |  |  |
| :--- | :--- | :--- | :--- | :--- |
|  | Powered Off | Disconnected, Disabled, Not <br> Configured, Resetting, Testing | Enabled, Transmit, <br> or TransmitR | Suspended, Resuming, <br> SendEOR, Restart_E/S |
| With | Off or amber if due to an <br> overcurrent condition | Off | Green | Off |
| Without | Off | Off or amber if due to an <br> overcurrent condition | Green | Off |

Table 2. Port Indicator Color Definitions in Manual Mode

| Color Definition | Port State |
| :--- | :--- |
| Off | Not operational |
| Amber | Error condition |
| Green | Fully operational |
| Blinking Off/Green | Software attention |
| Blinking Off/Amber | Hardware attention |
| Blinking Green/Amber | Reserved |

Note. Information presented in Table 1 and Table 2 is from USB 2.0 specification tables 11-6 and 11-7, respectively.

CY7C65640A

## Pin Configuration

Figure 1. 56-Pin Quad Flat Pack No Leads ( $8 \mathrm{~mm} \times 8 \mathrm{~mm}$ )


Table 3. CY7C65640APin Assignments

| Pin | Name | Type | Default | Description |
| :---: | :---: | :---: | :---: | :---: |
| 3 | VCC | Power | N/A | $\mathbf{V}_{\mathbf{C C}}$. This signal provides power to the chip. |
| 7 | VCC | Power | N/A | $\mathbf{V}_{\mathbf{C c}}$. This signal provides power to the chip. |
| 11 | VCC | Power | N/A | $\mathbf{V}_{\mathbf{C C}}$. This signal provides power to the chip. |
| 15 | VCC | Power | N/A | $\mathbf{V}_{\mathbf{C C}}$. This signal provides power to the chip. |
| 19 | VCC | Power | N/A | $\mathrm{V}_{\mathbf{C C}}$. This signal provides power to the chip. |
| 23 | VCC | Power | N/A | $\mathbf{V}_{\mathbf{C C}}$. This signal provides power to the chip. |
| 27 | VCC | Power | N/A | $\mathbf{V}_{\mathbf{c c}}$. This signal provides power to the chip. |
| 33 | VCC | Power | N/A | $\mathrm{V}_{\mathbf{C C}}$. This signal provides power to the chip. |
| 39 | VCC | Power | N/A | $\mathbf{V}_{\mathbf{C c}}$. This signal provides power to the chip. |
| 45 | VCC | Power | N/A | $\mathbf{V}_{\text {cce }}$. This signal provides power to the chip. |
| 55 | VCC | Power | N/A | $\mathrm{V}_{\mathbf{C C}}$. This signal provides power to the chip. |
| 4 | GND | Power | N/A | GND. Connect to Ground with as short a path as possible. |
| 8 | GND | Power | N/A | GND. Connect to Ground with as short a path as possible. |
| 12 | GND | Power | N/A | GND. Connect to Ground with as short a path as possible. |
| 16 | GND | Power | N/A | GND. Connect to Ground with as short a path as possible. |
| 20 | GND | Power | N/A | GND. Connect to Ground with as short a path as possible. |
| 24 | GND | Power | N/A | GND. Connect to Ground with as short a path as possible. |
| 28 | GND | Power | N/A | GND. Connect to Ground with as short a path as possible. |
| 34 | GND | Power | N/A | GND. Connect to Ground with as short a path as possible. |
| 40 | GND | Power | N/A | GND. Connect to Ground with as short a path as possible. |
| 47 | GND | Power | N/A | GND. Connect to Ground with as short a path as possible. |
| 50 | GND | Power | N/A | GND. Connect to Ground with as short a path as possible. |
| 56 | GND | Power | N/A | GND. Connect to Ground with as short a path as possible. |
| 21 | XIN | Input | N/A | 24 MHz Crystal IN or External Clock Input. |
| 22 | XOUT | Output | N/A | 24 MHz Crystal OUT. |
| 46 | RESET\# | Input | N/A | Active LOW Reset. This pin resets the entire chip. It is normally tied to $\mathrm{V}_{\mathrm{CC}}$ through a 100K resistor, and to GND through a $0.1 \mu \mathrm{~F}$ capacitor. Other than this, no other special power up procedure is required. |
| 26 | BUSPOWER | Input | N/A | VBUS. Connect to the VBUS pin of the upstream connector. This signal indicates to the hub that it is in a powered state, and may enable the D+ pull up resistor to indicate a connection. (The hub does so after the external EEPROM is read, unless it is put into a high speed mode by the upstream hub). The hub cannot be bus powered, and the VBUS signal must not be used as a power source. |
| SPI INTERFACE |  |  |  |  |
| 25 | SPI_CS | O | O | SPI Chip Select. Connect to CS pin of the EEPROM. |
| 48 | SPI_SCK | 0 | 0 | SPI Clock. Connect to EEPROM SCK pin. |
| 49 | SPI_SD | I/O/Z | Z | SPI Dataline Connect to GND with $15 \mathrm{~K} \Omega$ resistor and to the Data I/O pins of the EEPROM. |
| UPSTREAM PORT |  |  |  |  |
| 17 | D- | I/O/Z | Z | Upstream D- Signal. |
| 18 | D+ | I/O/Z | Z | Upstream D+ Signal. |

Table 3. CY7C65640APin Assignments (continued)

| Pin | Name | Type | Default | Description |
| :---: | :---: | :---: | :---: | :---: |
| DOWNSTREAM PORT 1 |  |  |  |  |
| 13 | DD-[1] | I/O/Z | Z | Downstream D- Signal. |
| 14 | DD+[1] | I/O/Z | Z | Downstream D+ Signal. |
| 36 | AMBER\#[1] | 0 | 1 | LED. Driver output for amber LED. Port Indicator Support. Active LOW. |
| 35 | GREEN\#[1] | O | 1 | LED. Driver output for green LED. Port Indicator Support. Active LOW. |
| 30 | OVR\#[1] | Input | 1 | Overcurrent Condition Detection Input. Active LOW. |
| 29 | PWR\#[1] | O/Z | Z | Power Switch Driver Output. Active LOW. |
| DOWNSTREAM PORT 2 |  |  |  |  |
| 9 | DD-[2] | I/O/Z | Z | Downstream D- Signal. |
| 10 | DD+[2] | I/O/Z | Z | Downstream D+ Signal. |
| 38 | AMBER\#[2] | 0 | 1 | LED. Driver output for amber LED. Port Indicator Support. Active LOW. |
| 37 | GREEN\#[2] | O | 1 | LED. Driver output for green LED. Port Indicator Support. Active LOW. |
| 32 | OVR\#[2] | Input | 1 | Overcurrent Condition Detection Input. Active LOW. |
| 31 | PWR\#[2] | O/Z | Z | Power Switch Driver Output. Active LOW. |
| DOWNSTREAM PORT 3 |  |  |  |  |
| 5 | DD-[3] | I/O/Z | Z | Downstream D- Signal. |
| 6 | DD+[3] | I/O/Z | Z | Downstream D+ Signal. |
| 42 | AMBER\#[3] | 0 | 1 | LED. Driver output for Amber LED. Port Indicator Support. Active LOW. |
| 41 | GREEN\#[3] | 0 | 1 | LED. Driver output for Green LED. Port Indicator Support. Active LOW. |
| 53 | OVR\#[3] | Input | 1 | Overcurrent Condition Detection Input. Active LOW. |
| 54 | PWR\#[3] | O/Z | Z | Power Switch Driver Output. Active LOW. |
| DOWNSTREAM PORT 4 |  |  |  |  |
| 1 | DD-[4] | I/O/Z | Z | Downstream D- Signal. |
| 2 | DD+[4] | I/O/Z | Z | Downstream D+ Signal. |
| 44 | AMBER\#[4] | 0 | 1 | LED. Driver output for Amber LED. Port Indicator Support. Active LOW. |
| 43 | GREEN\#[4] | O | 1 | LED. Driver output for Green LED. Port Indicator Support. Active LOW. |
| 51 | OVR\#[4] | Input | 1 | Overcurrent Condition Detection Input. Active LOW. |
| 52 | PWR\#[4] | O/Z | Z | Power Switch Driver Output. Active LOW. |

Unused port DD+/DD- lines can be left floating. The port power, amber, and green LED pins should be left unconnected, and the overcurrent pin should be tied high. The overcurrent pin is an input and it should not be left floating.

## Default Descriptors

## Device Descriptor

The standard device descriptor for TetraHub is based on the VID, PID, and DID found in the SPI EEPROM. This VID/PID/DID in the EEPROM overwrites the default VID/PID/DID. If no EEPROM is used, the TetraHub enumerates with the following default descriptor values.
Table 4. Tetra Hub Descriptor Values

| Byte | Full Speed | High Speed | Field Name | Description |
| :---: | :---: | :---: | :--- | :--- |
| 0 | $0 \times 12$ | $0 \times 12$ | bLength | 18 Bytes |
| 1 | $0 \times 01$ | $0 \times 01$ | bDescriptorType | DEVICE_DESCRIPTOR |
| 2,3 | $0 \times 0200$ | $0 \times 0200$ | bcdUSB | USB specification 2.0 |
| 4 | $0 \times 09$ | $0 \times 09$ | bDeviceClass | HUB |
| 5 | $0 \times 00$ | $0 \times 00$ | bDeviceSubClass | None |
| 6 | $0 \times 00$ | $0 \times 02$ | bDeviceProtocol | None |
| 7 | $0 \times 40$ | $0 \times 40$ | bMaxPacketSize0 | 64 bytes |
| 8,9 | $0 \times 04 B 4$ | $0 \times x 04 B 4$ | wIdVendor | VID (overwritten by what is defined in EEPROM) |
| 10,11 | $0 \times 6560$ | $0 \times 6560$ | wIdProduct | PID (overwritten by what is defined in EEPROM) |
| 12,13 | $0 \times 000 B$ | $0 \times 000 B$ | wbcdDevice | DID (overwritten by what is defined in EEPROM) |
| 14 | $0 \times 00$ | $0 \times 00$ | iManufacturer | No manufacturer string supported |
| 15 | $0 \times 00$ | $0 \times 00$ | iProduct | No product string supported |
| 16 | $0 \times 00$ | $0 \times 00$ | iSerialNumber | No serial string supported |
| 17 | $0 x 01$ | $0 \times 01$ | bNumConfigurations | One configuration supported |

Table 5. Configuration Descriptor

| Byte | Full Speed | High Speed | Field Name | Description |
| :---: | :---: | :---: | :--- | :--- |
| 0 | $0 \times 09$ | $0 \times 09$ | bLength | 9 Bytes |
| 1 | $0 \times 02$ | $0 \times 02$ | bDescriptorType | CONFIG_DESCRIPTOR |
| 2 | $0 \times 0019$ | $0 \times 0029^{[1]}$ | wTotalLength | Length of all other descriptors |
| 4 | $0 \times 01$ | $0 \times 01$ | bNumInterfaces | 1 |
| 5 | $0 \times 01$ | $0 \times 01$ | bConfigurationValue | The configuration to be used |
| 6 | $0 \times 00$ | $0 \times 00$ | iConfiguration |  |
| 7 | $0 \times E 0$ | $0 \times E 0$ | bmAttributes |  |
| 8 | $0 \times 32$ | $0 \times 32^{[2]}$ | bMaxPower |  |

Table 6. Interface Descriptor

| Byte | Full Speed | High Speed | Field Name |  |
| :---: | :---: | :---: | :--- | :--- |
| 0 | $0 \times 09$ | $0 \times 09$ | bLength | Description |
| 1 | $0 \times 04$ | $0 \times 04$ | bDescriptorType | Bytes |
| 2 | $0 \times 00$ | $0 \times 00$ | bInterfaceNumber |  |
| 3 | $0 \times 00$ | $0 \times 00$ | bAlternateSetting |  |
| 4 | $0 \times 01$ | $0 \times 01$ | bNumEndpoints |  |
| 5 | $0 \times 09$ | $0 \times 09$ | blnterfaceClass |  |
| 6 | $0 \times 00$ | $0 \times 00$ | bInterfaceSubClass |  |
| 7 | $0 \times 00$ | $0 \times 01$ | bInterfaceProtocol |  |
| 8 | $0 \times 00$ | $0 \times 00$ | ilnterface |  |

[^0]Table 7. Endpoint Descriptor

| Byte | Full Speed | High Speed | Field Name |  |
| :---: | :---: | :---: | :--- | :--- |
| 0 | $0 \times 07$ | $0 \times 07$ | bLength | Description |
| 1 | $0 \times 05$ | $0 \times 05$ | bDescriptorType | ENDPOINT_DESCRIPTOR |
| 2 | $0 \times 81$ | $0 \times 81$ | bEndpointAddress | IN Endpoint \#1 |
| 3 | $0 \times 03$ | $0 \times 03$ | bmAttributes | Interrupt |
| 4,5 | $0 \times 0001$ | $0 \times 0001$ | wMaxPacketSize | Maximum packet size |
| 6 | $0 \times F F$ | $0 \times 0 \mathrm{C}$ | bInterval | Polling rate |

Table 8. Interface Descriptor ${ }^{[3]}$

| Byte | Full Speed | High Speed | Field Name | Description |
| :---: | :---: | :---: | :--- | :--- |
| 0 | N/A | $0 \times 09$ | bLength | 9 Bytes |
| 1 | N/A | $0 \times 04$ | bDescriptorType | INTERFACE_DESCRIPTOR |
| 2 | N/A | $0 \times 00$ | bInterfaceNumber | Interface descriptor index |
| 3 | N/A | $0 \times 01$ | bAlternateSetting | Alternate setting for the interface |
| 4 | N/A | $0 \times 01$ | bNumEndpoints | Number of endpoints defined |
| 5 | N/A | $0 \times 09$ | bInterfaceClass | Interface class |
| 6 | N/A | $0 \times 00$ | bInterfaceSubClass | Interface sub-class |
| 7 | N/A | $0 \times 02$ | bInterfaceProtocol | Interface protocol |
| 8 | N/A | $0 \times 00$ | bInterface | Interface string index |

Table 9. Endpoint Descriptor ${ }^{[3]}$

| Byte | Full Speed | High Speed | Field Name | Description |
| :---: | :---: | :---: | :--- | :--- |
| 0 | N/A | $0 \times 07$ | bLength | 7 Bytes |
| 1 | N/A | $0 \times 05$ | bDescriptorType | ENDPOINT_DESCRIPTOR |
| 2 | N/A | $0 \times 81$ | bEndpointAddress | IN Endpoint \#1 |
| 3 | N/A | $0 \times 03$ | bmAttributes | Interrupt |
| 4,5 | N/A | $0 \times 0001$ | wMaxPacketSize | Maximum packet size |
| 6 | N/A | $0 \times 0 \mathrm{C}$ | bInterval | Polling rate |

Table 10. Device Qualifier Descriptor

| Byte | Full Speed | High Speed | Field Name | Description |
| :---: | :---: | :---: | :--- | :--- |
| 0 | $0 \times 0$ A | $0 \times 0 \mathrm{~A}$ | bLength | 10 Bytes |
| 1 | $0 \times 06$ | $0 \times 06$ | bDescriptorType | DEVICE_QUALIFIER |
| 2,3 | $0 \times 0200$ | $0 \times 0200$ | bcdUSB |  |
| 4 | $0 \times 09$ | $0 \times 09$ | bDeviceClass |  |
| 5 | $0 \times 00$ | $0 \times 00$ | bDeviceSubClass |  |
| 6 | $0 \times 02$ | $0 \times 00$ | bDeviceProtocol |  |
| 7 | $0 \times 40$ | $0 \times 40$ | bMaxPacketSize0 |  |
| 8 | $0 \times 01$ | $0 \times 01$ | bNumConfigurations |  |
| 9 | $0 \times 00$ | $0 \times 00$ | bReserved |  |

Note
3. If TetraHub is configured for single-TT only (from the external EEPROM), this descriptor is not present.

Table 11. Hub Descriptor

| Byte | All Speeds | Field Name | Description |
| :---: | :---: | :---: | :---: |
| 0 | 0x09 | bLength | 9 Bytes |
| 1 | 0x29 | bDescriptorType | HUB descriptor |
| 2 | $0 \times 04{ }^{[11]}$ | bNbrPorts | Number of ports supported |
| 3,4 | 0x0089 ${ }^{[11]}$ | wHubCharacteristics | b1, b0: Logical Power Switching Mode <br> 00: Ganged power switching (all ports' power at once) <br> 01: Individual port power switching (Default in TetraHub) <br> b2: Identifies a Compound Device, <br> 0 : Hub is not part of a compound device (Default in TetraHub), <br> 1: Hub is part of a compound device. <br> b4, b3: Overcurrent protection mode <br> 00: Global overcurrent protection. The hub reports overcurrent as a summation of all ports current draw, without a breakdown of individual port overcurrent status. <br> 01: Individual port overcurrent protection. The hub reports overcurrent on a per-port basis. Each port has an overcurrent status (Default in TetraHub). <br> 1X: No overcurrent protection. This option is enabled only for buspowered hubs that do not implement overcurrent protection. <br> b6, b5: TT Think Time <br> 00: TT requires at most 8 FS bit times of inter transaction gap on a full/low speed downstream bus (Default in TetraHub). <br> 01: TT requires at most 16 FS bit times. <br> 10: TT requires at most 24 FS bit times. <br> 11: TT requires at most 32 FS bit times. <br> b7: Port indicators supported, <br> 0 : Port indicators are not supported on its downstream facing ports and the PORT_INDICATOR request has no effect. <br> 1: Port indicators are supported on its downstream facing ports and the PORT_INDICATOR request controls the indicators. <br> b15...b8: Reserved |
| 5 | $0 \times 32^{[11]}$ | bPwrOn2PwrGood | Time from when the port is powered to when the power is good on that port |
| 6 | $0 \times 64^{[11]}$ | bHubContrCurrent | Maximum current requirement for the hub controller |
| 7 | $0 \times 00^{[11]}$ | bDeviceRemovable | Indicates if the port has a removable device attached |
| 8 | $0 \times F F^{[1]}$ | bPortPwrCtrIMask | Required for compatibility with software written for 1.0 compliant devices |

Note
4. This value is configured through the External EEPROM.

## Configuration Options

Systems using TetraHub must have an external EEPROM for the device to have a unique VID, PID, and DID. The TetraHub can talk to SPI EEPROM that are double byte addressable only. TetraHub uses the command format from the '040 parts. The TetraHub cannot talk to ' 080 EEPROM parts, as the read command format used for talking to ' 080 is not the same as ' 040 . The '010s and '020s uses the same command format as used to interface with the ' 040 and hence these can also be used to interface with the TetraHub.

## Default - 0xD0 Load

When used in default mode, only a unique VID, PID, and DID must be present in the external SPI EEPROM. The contents of the EEPROM must contain this information in the following format:

| Byte | Value |
| :---: | :---: |
| 0 | 0xD0 |
| 1 | VID (LSB) |
| 2 | VID (MSB) |
| 3 | PID (LSB) |
| 4 | PID (MSB) |
| 5 | DID (LSB) |
| 6 | DID (MSB) |

## Configured - 0xD2 Load

| Byte | Value (MSB->LSB) |
| :---: | :---: |
| 0 | OxD2 |
| 1 | VID (LSB) |
| 2 | VID (MSB) |
| 3 | PID (LSB) |
| 4 | DID (LSB) |
| 5 | DID (MSB) |
| 6 | Timer[3:0] |

## Byte 0: 0xD2

Needs to be programmed with 0xD2

## Byte 1: VID (LSB)

Least Significant Byte of Vendor ID

## Byte 2: VID (MSB)

Most Significant Byte of Vendor ID
Byte 3: PID (LSB)
Least Significant Byte of Product ID

## Byte 4: PID (MSB)]

Most Significant Byte of Product ID
Byte 5: DID (LSB)
Least Significant Byte of Device ID
Byte 6: DID (MSB)]
Most Significant Byte of Device ID

## Byte 7: EnableOvercurrentTimer[3:0], DisabledOvercurrent-

 Timer[3:0]Count time in ms for filtering overcurrent detection. Bits 7-4 are for an enabled port, and bits 3-0 are for a disabled port. Both range from 0 ms to 15 ms . See "Port Indicators" on page 5. Default: $8 \mathrm{~ms}=0 \times 88$.
Byte 8: ActivePorts[3:0], RemovablePorts[3:0]
Bits 7-4 are the ActivePorts[3:0] bits that indicates if the corresponding port is usable. For example, a two-port hub that uses ports 1 and 4 sets this field to $0 \times 09$. The total number of ports reported in the hub descriptor: bNbrPorts field is calculated from this. Bits 3-0 are the RemovablePorts[3:0] bits that indicates whether the corresponding port is removable (set to HIGH). This bit's values are recorded appropriately in the HubDescriptor:DeviceRemovable field. Default: 0xFF.

## Byte 9: MaximumPower

This value is reported in the ConfigurationDescriptor:bMaxPower field and is the current in 2 mA intervals that is required from the upstream hub. Default: $0 \times 32=100 \mathrm{~mA}$

## Byte 10: HubControllerPower

This value is reported in the HubDescriptor:bHubContrCurrent field and is the current in milliamperes required by the hub controller. Default: 0x64 $=100 \mathrm{~mA}$.

## Byte 11: PowerOnTimer

This value is reported in the HubDescriptor:bPwrOn2PwrGood field and is the time in 2 ms intervals from the SetPortPower command until the power on the corresponding downstream port is good. Default: $0 \times 32=100 \mathrm{~ms}$.
Byte 12: IllegalHubDescriptor, Unused, FullspeedOnly, NoPortIndicators, Reserved, GangPowered, SingleTTOnly, NoEOPatEOF1

Bit 7: IllegalHubDescriptor: For GetHubDescriptor request, some USB hosts use a DescriptorTypeof 0x00 instead of HUB_DESCRIPTOR, 0x29. According to the USB 2.0 standard, a hub must treat this as a Request Error, and stall the transaction accordingly (USB 2.0, 11.24.2.5). For systems that do not accept this, the IllegalHubDescriptor configuration bit may be set to enable TetraHub to accept a DescriptorType of $0 \times 00$ for this command. Default is 0 , recommended setting is 1 .

Bit 6: Unused: This bit is an unused, 'don't care' bit and can be set to anything.
Bit 5: Fullspeed: Only configures the hub to be a full speed only device. Default set to 0 .
Bit 4: NoPortIndicators: Turns off the port indicators and does not report them as present in the HubDescriptor, wHubCharacteristics b7 field. Default set to 0 .
Bit 3: Reserved: This bit is reserved and should not be set to 1. Must be set to 0 .

Bit 2: GangPowered: Indicates whether the port power switching is ganged (set to 1 ) or per-port (set to 0 ). This is
reported in the HubDescriptor, wHubCharacteristics field, b4, b3, b1, and b0. Default set to 0 .

Bit 1: SingleTTOnly: Indicates that the hub should only support single transaction translator mode. This changes various descriptor values. Default set to 0 .
Bit 0: NoEOPatEOF1 turns off the EOP generation at EOF1 in full speed mode. Note that several USB 1.1 hosts cannot handle EOPatEOF1 properly. Cypress recommends that this option be turned off for general purpose hubs. Default is 0 , recommended setting is 1 .

## Supported USB Requests

## Device Class Commands

Table 12. Device Class Requests

| Request | bmRequestType | bRequest | wValue | wIndex | wLength | Data |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| GetDeviceStatus | 10000000B | $0 \times 00$ | 0x0000 | 0x0000 | 0x0002 | 2 Byte Device Status |
| GetInterfaceStatus | 10000001B | 0x00 | 0x0000 | 0x0000 | 0x0002 | 2 Byte Endpoint Status |
| GetEndpointStatus | 10000010B | $0 \times 00$ | 0x0000 | 0x0000 | 0x0002 | 2 Byte Endpoint Status |
| GetDeviceDescriptor | 10000000B | $0 \times 06$ | 0x0001 | Zero or Language ID | Descriptor Length | Descriptor |
| GetConfigDescriptor | 10000000B | $0 \times 06$ | 0x0002 | Zero or Language ID | Descriptor Length | Descriptor |
| GetDeviceQualifierDescriptor | 10000000B | $0 \times 06$ | $0 \times 0006$ | Zero or Language ID | Descriptor Length | Descriptor |
| GetOtherSpeedConfigurationDescriptor | 10000000B | $0 \times 06$ | 0x0007 | Zero or Language ID | Descriptor Length | Descriptor |
| GetConfiguration ${ }^{[5]}$ | 10000000B | $0 \times 08$ | 0x0000 | 0x0000 | 0x0001 | Configuration value |
| SetCongfiguration ${ }^{[5]}$ | 00000000B | $0 \times 09$ | Configuration Value | 0x0000 | 0x0000 | None |
| GetInterface | 10000001B | 0xA | 0x0000 | 0x0000 | 0x0001 | Interface Number |
| SetInterface | 00000001B | 0x0B | Alternate Setting | Interface Number | 0x0000 | None |
| SetAddress | 00000000B | $0 \times 05$ | Device Address | 0x0000 | 0x0000 | None |
| SetDeviceRemoteWakeup | 00000000B | $0 \times 03$ | 0x01 | 0x0000 | 0x0000 | None |
| SetDeviceTest_J | 00000000B | $0 \times 03$ | 0x02 | 0x0100 | 0x0000 | None |
| SetDeviceTest_K | 00000000B | $0 \times 03$ | 0x02 | 0x0200 | 0x0000 | None |
| SetDeviceTest_SEO_NAK | 00000000B | $0 \times 03$ | 0x02 | 0x0300 | 0x0000 | None |
| SetDeviceTest_Packet | 00000000B | $0 \times 03$ | 0x02 | 0x0400 | 0x0000 | None |
| SetEndpointHalt | 00000000B | $0 \times 03$ | 0x00 | 0x0000 | 0x0000 | None |
| ClearDeviceRemoteWakeup | 00000000B | $0 \times 01$ | 0x01 | 0x0000 | 0x0000 | None |
| ClearEndpointHalt | 00000000B | $0 \times 01$ | 0x00 | 0x0000 | 0x0000 | None |

[^1]
## Hub Class Commands

Table 13. Hub Class Requests

| Request | bmRequestType | bRequest | wValue | wIndex | wLength | Data |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| GetHubStatus | 10100000B | $0 \times 00$ | 0x0000 | 0x0000 | 0x0004 | Hub Status (See Table 11-19 of Spec) Change Status (See Table 11-20 of Spec) |
| GetPortStatus | 10100011B | $0 \times 00$ | 0x0000 | Byte 0: 0x00 <br> Byte 1: Port | 0x0004 | Port Status (See Table 11-21 of Spec) Change Status (See Table 11-20 of Spec) |
| ClearHubFeature | 00100000B | $0 \times 01$ | Feature Selectors ${ }^{[6]}$ 0 or 1 | 0x0000 | 0x0000 | None |
| ClearPortFeature | 00100011B | $0 \times 01$ | Feature Selectors ${ }^{[6]}$ $1,2,8,16,17,18,19$, or 20 | Byte 0: 0x00 <br> Byte 1: Port | 0x0000 | None |
| ClearPortFeature | 00100011B | $0 \times 01$ | $\begin{array}{\|l\|} \hline \text { Feature } \\ \text { Selectors }{ }^{[6]} 22 \\ \text { (PORT_INDICATOR) } \end{array}$ | Byte 0: <br> Selectors ${ }^{[7]}$ <br> $0,1,2$, or 3 <br> Byte 1: Port | 0x0000 | None |
| SetHubFeature | 00100000B | $0 \times 03$ | Feature Selector ${ }^{[6]}$ | 0x0000 | 0x0000 | TetraHub STALLs this request |
| SetPortFeature | 00100011B | $0 \times 03$ | Feature Selectors ${ }^{[6]}$ 2, 4 or 8 | Port | 0x0000 | None |
| SetPortFeature | 00100011B | $0 \times 03$ | $\begin{aligned} & \hline \text { Feature } \\ & \text { Selector }^{[6]} 21 \\ & \text { (PORT_TEST) }^{2} \end{aligned}$ | Byte 0: <br> Selectors ${ }^{[8]}$ <br> 1,2, 3, 4 or 5 <br> Byte 1: Port | 0x0000 | None |
| SetPortFeature | 00100011B | $0 \times 03$ | Feature <br> Selector ${ }^{[6]} 22$ <br> (PORT_INDICATOR) | Byte 0: Selectors ${ }^{[7]}$ $0,1,2$, or 3 Byte 1: Port | 0x0000 | None |
| GetHubDescriptor | 10100000B | $0 \times 06$ | Descriptor Type and Descriptor Index |  | Hub Descriptor Length |  |
| ClearTTBuffer | 00100011B | $0 \times 08$ | Dev_Addr, EP_Num | TT_Port | 0x0000 | None |
| ResetTT | 00100000B | $0 \times 09$ | 0x0000 | Byte 0: 0x00 <br> Byte 1: Port | 0x0000 | None |
| GetTTState | 10100011B | OXOA | TT_Flags | Byte 0: 0x00 <br> Byte 1: Port | TT State Length | TT State |
| StopTT | 00100011B | 0x0B | 0x0000 | Byte 0: 0x00 <br> Byte 1: Port | 0x0000 | None |

[^2]Table 14. Hub Class Feature Selector

| Feature Selector | Recipient | Value |
| :--- | :---: | :---: |
| C_HUB_LOCAL_POWER | Hub | 0 |
| C_HUB_OVER_CURRENT | Hub | 1 |
| PORT_CONNECTION | Port | 0 |
| PORT_ENABLE | Port | 1 |
| PORT_SUSPEND | Port | 2 |
| PORT_RESET | Port | 4 |
| PORT_POWER | Port | 8 |
| PORT_LOW_SPEED | Port | 9 |
| C_PORT_CONNECTION | Port | 16 |
| C_PORT_ENABLE | Port | 17 |
| C_PORT_SUSPEND | Port | 18 |
| C_PORT_OVER_CURRENT | Port | 19 |
| C_PORT_RESET | Port | 20 |
| PORT_TEST | Port | 21 |
| PORT_INDICATOR | Port | 22 |

Table 15. Test Mode Selector for Feature Selector PORT_TEST (0x21)

| PORT_TEST Mode Description | Selector Value |
| :--- | :---: |
| Test_J | 1 |
| Test_K | 2 |
| Test_SE0_NAK | 3 |
| Test_Packet | 4 |
| Test_Force_Enable | 5 |

Table 16. Port Indicator Selector for Feature Selector PORT_INDICATOR (0x22)

| Port Indicator Color | Selector <br> Value | Port Indicator <br> Mode |
| :--- | :---: | :--- |
| Color Set Automatically as <br> shown in Table 1 | 0 | Automatic <br> Mode |
| Amber | 1 | Manual Mode |
| Green | 2 | Manual Mode |
| Off | 3 | Manual Mode |

## Upstream USB Connection

The following is a schematic of the USB upstream connector.
Figure 2. USB Upstream Port Connection


## Downstream USB Connections

The following is a schematic of the USB downstream connector.
Figure 3. USB Downstream Port Connection


## LED Connections

The following is a schematic of the LED circuitry.
Figure 4. USB Downstream Port Connection


## Sample Schematic

Figure 5. Sample Schematic


## Maximum Ratings

Storage Temperature .............................. $-65^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$
Ambient Temperature
with Power Applied $\ldots \ldots . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . ~$
0 ${ }^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$.

Static Discharge Voltage
2000 V
Maximum Output Sink Current per I/O 10 mA

## Operating Conditions

| $\mathrm{T}_{\mathrm{A}}$ (Ambient Temperature Under Bias) | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ |
| :---: | :---: |
| Supply Voltage | +3.45 |
| Ground Voltage. | .. 0 V |
| C (Oscillator or Crystal Frequen |  |

## DC Electrical Characteristics

| Parameter | Description | Conditions | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\mathrm{CC}}$ | Supply Voltage |  | 3.15 | 3.3 | 3.45 | V |
| $\mathrm{V}_{\text {IH }}$ | Input High Voltage |  | 2 |  | 5.25 | V |
| $\mathrm{V}_{\mathrm{IL}}$ | Input Low Voltage |  | -0.5 |  | 0.8 | V |
| II | Input Leakage Current | $0<\mathrm{V}_{\text {IN }}<\mathrm{V}_{\text {CC }}$ |  |  | $\pm 10$ | $\mu \mathrm{A}$ |
| $\mathrm{V}_{\mathrm{OH}}$ | Output Voltage High | $\mathrm{I}_{\text {OUT }}=4 \mathrm{~mA}$ | 2.4 |  |  | V |
| $\mathrm{V}_{\mathrm{OL}}$ | Output Low Voltage | $\mathrm{I}_{\text {OUT }}=-4 \mathrm{~mA}$ |  |  | 0.4 | V |
| ${ }^{\text {OH }}$ | Output Current High |  |  |  | 4 | mA |
| ${ }^{\text {OL }}$ | Output Current Low |  |  |  | 4 | mA |
| $\mathrm{C}_{\text {IN }}$ | Input Pin Capacitance |  |  |  | 10 | pF |
| ISUSP | Suspend Current |  |  | 100 |  | $\mu \mathrm{A}$ |
| ${ }^{\text {c }}$ c | Supply Current |  |  |  |  |  |
|  | 4 Active ports | Full speed Host, Full speed Devices |  | 255 |  | mA |
|  |  | High speed Host, High speed Devices |  | 460 |  | mA |
|  |  | High speed Host, Full speed Devices |  | 395 |  | mA |
|  | 2 Active Ports | Full speed Host, Full speed Devices |  | 255 |  | mA |
|  |  | High speed Host, High speed Devices |  | 415 |  | mA |
|  |  | High speed Host, Full speed Devices |  | 380 |  | mA |
|  | No Active Ports | Full speed Host |  | 255 |  | mA |
|  |  | High speed Host |  | 370 |  | mA |
| USB Transceiver |  |  |  |  |  |  |
| Z ${ }_{\text {HSDRV }}$ | Driver Output Resistance |  | 41 | 45 | 49 | $\Omega$ |
| $\mathrm{I}_{\mathrm{i}}$ | Input Leakage Current |  |  | $\pm 0.1$ | $\pm 5$ | $\mu \mathrm{A}$ |
| $\mathrm{l}_{\mathrm{Oz}}$ | Three-state Output OFF-State Current |  |  |  | $\pm 10$ | $\mu \mathrm{A}$ |
| $\mathrm{V}_{\text {HSRS }}$ | High speed Receiver Sensitivity Level |  | 210 |  |  | mV |
| $\mathrm{T}_{\text {rfi }}$ | Full speed Frame Jitter |  |  |  | 133 | ns |
| Thermal Resistance |  |  |  |  |  |  |
| $\mathrm{T}_{\text {JA }}$ | Theta Thermal Coefficient Junction to Ambient | E-Pad configuration in section at zero airflow | 23.27 |  |  | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |

## AC Electrical Characteristics

Both the upstream USB transceiver and all four downstream transceivers have passed the USB-IF USB 2.0 Electrical Certification Testing.
Table 17. Serial Peripheral Interface

| Parameter | Description | Conditions | Min | Typ | Max | Unit |
| :---: | :--- | :--- | :--- | :---: | :---: | :---: |
|  | Clock Rise/Fall Time |  |  |  | 500 | ns |
|  | Clock Frequency |  |  |  | 250 | kHz |
|  | Data Setup Time |  | 50 |  |  | ns |
|  | Hold Time |  | 100 |  |  | ns |
|  | Reset period | 1.9 |  | ms |  |  |

Figure 6. Eye Diagram


CY7C65640A

## Ordering Information

| Ordering Code | Package Type |
| :--- | :--- |
| CY7C65640A-LFXC | $56-$ pin QFN Pb-free Package |
| CY7C65640A-LTXC | $56-$ pin QFN Sawn type Pb-free Package |
| CY7C65640A-LTXCT | 56-pin QFN Sawn type Pb-free Package |
| CY4602 | TetraHub USB 2.0 4 port Hub Reference Design Kit |

## Package Diagram

The TetraHub is available in a space-saving 56-pin QFN $(8 \times 8 \mathrm{~mm})$
Figure 7. $56-$ Pin QFN $8 \times 8 \mathrm{~mm}$


Figure 8. 56-Pin Sawn QFN (8X8X1.0 mm)


Note. The bottom metal pad size varies by product due to die size variable. If metal pad design or dimension are critical with your board designs, contact a Cypress Sales office to get the specific outline option.

## Quad Flat Package No Leads (QFN) Package Design Notes

The QFN (Quad Flatpack No Leads), being a lead free package, the electrical contact of the part to the printed circuit board (PCB) is made by soldering the lands on the bottom surface of the package to the PCB. Hence special attention is required for the heat transfer area below the package to provide a good thermal bond to the circuit board. A Copper (Cu) fill should be designed into the PCB as a thermal pad under the package. Heat is transferred from the TetraHub through the device's metal paddle on the bottom side of the package. Heat from here is conducted to the PCB at the thermal pad. It is then conducted from the thermal pad to the PCB inner ground plane by a $5 \times 5$ array of via. A via is a plated through-hole in the PCB with a finished diameter of 13 mil. The QFN's metal die paddle must be soldered to the PCB's thermal pad. Solder mask is placed on the board top side over each via to resist solder flow into the via. The mask on the top side also minimizes outgassing during the solder reflow process.

Follow the layout guidelines provided in the PCB layout files accompanied with the CY4602 TetraHub Reference Design Kit. The information in this section was derived from the original application note by the package vendor. For further information on this package design, refer to the application note on Surface Mount Assembly of Amkor's MicroLeadFrame (MLF) Technology. You can find this on Amkor's website at this URL: http://www.amkor.com/products/notes_papers/MLF_AppNote. This application note provides detailed information on board mounting guidelines, soldering flow, rework process, and so on.
Figure 9 on page 22 displays a cross-sectional area underneath the package. The cross section is of only one via. The solder paste template needs to be designed to enable at least 50 percent solder coverage. The thickness of the solder paste template should be 5 mil. It is recommended that 'No Clean', type 3 solder paste is used for mounting the part. Nitrogen purge is recommended during reflow.

Figure 9. Cross section of Area Below the QFN Package


Figure 10 is a plot of the solder mask pattern and Figure 11 displays an X-Ray image of the assembly (darker areas indicate solder).

Figure 10. Plot of the Solder Mask (White Area)


Figure 11. X-Ray Image of the Assembly


## Document History Page

| Document Title: CY7C65640A TetraHub ${ }^{\text {TM }}$ High Speed USB Hub Controller Document Number: 38-08019 |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Rev. | ECN No. | Submission Date | Orig. of Change | Description of Change |
| ** | 113506 | 04/25/02 | BHA | New Data Sheet (preliminary) |
| *A | 116812 | 08/15/02 | MON | Supply voltage range changed from $3.3 \mathrm{~V}-3.6 \mathrm{~V}$ to $3.15 \mathrm{~V}-3.45$ Added EPROM types that can be used with HX2 (p. 14) Added description of bit 7 of Byte 12 (Illegal Hub Descriptor) D2 Load (p. 15) Added high speed sensitivity level of receiver (p. 20) Added QFN package design notes (section 16.1) |
| *B | 118518 | 10/31/02 | MON | Fixed the Spec field in the Default Device Descriptor section 7.1 Fixed Interface Protocol field of the interface descriptor, section 7.3 Fixed Device Protocol field of the interface descriptor, section 7.7 Modified table 9-2, section 9.2 <br> Added table 9-4, 9-5, section 9.2 <br> Added table 4-1, 4-2, section 4.8 <br> Added information on bits in wHubCharacterestics, section 7.8 Modified figure $16-1$ in QFN package design notes, section 16.1 Included the eye diagram, section 14.4.2 <br> Preliminary to Final |
| *C | 121793 | 12/09/02 | MON | Fixed the SPI clock Frequency to 250 KHz , section 14.4.1 <br> Added information on the configuration of unused port pins, section 6.0 <br> Added statement that no special power up procedure is required, section 6.0 |
| *D | 125275 | 04/02/03 | MON | Changed the name of Bit 3 of Byte 12 of EEPROM for a 0xD2 load (section 8.2) from BusPowered to Reserved. <br> Removed all indication to the misconception that the hub can support bus power. Added information as to which nibble of byte 8 in the EEPROM defines the active ports and which nibble defines the removable ports, section 8.2. <br> Added further information on the BUSPOWER pin (pin 26) functionality in section 6.0. |
| *E | 234272 | see ECN | MON | Added part number for the lead free package (CY7C65640-LFXC), section 15.0 Changed the name of Bit 6 of Byte 12 of EEPROM for a 0xD2 load from CompoundDevice to Unused, section 8.2. |
| *F | 285171 | see ECN | KKU | Changed CY7C65640 to CY7C65640A and reformatted to new format |
| *G | 308296 | see ECN | KKU | Added reset period under AC characteristics. Removed compound device from features list. Updated section 7.1 DID from $0 \times 0007$ to $0 \times 000 \mathrm{~B}$ for rev E silicon. |
| *H | 390258 | see ECN | KKU | Added theta thermal coefficient junction to ambient ( $\mathrm{T}_{\text {JA }}$ ) to section 14.3 |
| * | 522224 | see ECN | TEH | Corrected typo in table 6-1. Changed downstream port 4 signal labels from [3] to [4]. Updated package diagram. Updated to new template. |
| *J | 2657415 | 02/10/09 | DPT/PYRS | Added package diagram spec 51-85187, updated package diagram spec 51-85144 and updated Ordering Information table |
| *K | 2742387 | 07/22/09 | DPT | Updated 56 QFN (sawn) package drawing |
| *L | 2766203 | 09/18/09 | DPT | Updated 56-Pin Sawn QFN package (Flgure 8) |
| *M | 2825358 | 12/10/09 | RSKVIPYRS | Added Contents. Added 'Pb-free Package' for Sawn parts in the Ordering Information table. |

CY7C65640A

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[^0]:    Notes

    1. This value is reported as $0 \times 19$ if the hub is configured in Single-TT mode.
    2. This value is configured through the External EEPROM.
[^1]:    Note
    5. Only one configuration is supported in TetraHub.

[^2]:    Notes
    6. Feature selector values for different features are presented in Table 14
    7. Selector values for different features are presented in Table 16.
    8. Selector values for different features are presented in Table 15.

